

CT Commande Prédictive Non Linéaire

November 16th, 2023

ESISAR Valence



Laboratoire de Conception
et d'Intégration des Systèmes



Agenda

9h30-10h: Welcome and introduction

- 10h00-10h30: Maintaining a relevant dataset for data-driven MPC using Willems' fundamental lemma extensions
Alexandre Faye-Bédrin, Stanislav Aranovskiy, Paul Chauchat, Romain Bourdais (IETR - CentraleSupélec)
- 10h30-11h: Nonlinear MPC for collision-avoidance trajectory tracking of a multi-UAV system in a mapping mission
Dora Novak, Sihem Tebbani (L2S - CentraleSupélec)
- 11h-11h30 : Solving MPC problems using ramp functions
Morten Hovd (NUST)

11h45 – 13h45: Lunch break & Esisarium platform visit

- 13h50 – 14h20: Distributed Moving Horizon Estimation with pre-estimation using EKF for Nonlinear Measurements
Matthieu Borelle, Sylvain Bertrand, Cristina Stoica, Teodoro Alamo, Eduardo F. Camacho (ONERA – L2S – CentraleSupélec – Univ. Séville)
- 14h20 – 15h05: A (small) step towards a systematic design of NMPC effective and implementable setting
Mazen Alamir (CNRS, GIPSAlab, Grenoble INP)
- 15h05 – 15h50: Distributed predictive control based on Gaussian process models
Alexandra Grancharova (Univ. of Chemical Technology and Metallurgy)

15h50-16h: Coffee break

- 16h-16h30: Computer-generated Control Lyapunov Function via offline linear programming
Huu-Thinh Do, Franco Blanchini, Stefano Miani, Ionela Prodan (Grenoble INP – LCIS - Università di Udine)
- 16h30-17h: Terminal region enlargement of a stabilizing NMPC design for a multicopter
Huu Thien Nguyen, Ngoc Thinh Nguyen, Ionela Prodan (SYSTECH-ISR – Univ. of Porto – Univ. of Luebeck, Grenoble INP – LCIS)
- 17h-17h30: Mixed-integer predictive control for a three-phase electric arc furnace producing Silico Manganese
Minh Tuan Dinh, Ionela Prodan, Olivier Lesage, Eduardo Mendes (Grenoble INP – LCIS – Eramet Ideas)

CT CPNL organization

- Use of ML: cpnl@sagip.org
 - Share news, CFP, offers (jobs, PhD, Master), etc.
- Subscribe to the mailing list of CT CPNL: via SAGIP website
 - Subscribe to SAGIP (<http://www.sagip.org/fr/inscription-mode-demploi>)
 - Account opening -> Choose your CT of interest
- CT CPL website: ct-cpnl.fr



CT Commande Prédictive Non-Linéaire

French Research Group in Non Linear Model Predictive Control

Actualités Evenements Animateurs Partenaires Membres Offres Search

CT CPNL

Les objectifs principaux de ce groupe de travail sont premièrement d'animer, de valoriser et de transférer la méthodologie associée aux techniques de commande et d'estimation basées sur l'horizon glissant au sein de la communauté automatique nationale et deuxièmement d'explorer les verrous scientifiques.

Objectifs scientifiques du groupe de travail

Animer, valoriser et transférer la méthodologie au sein de la communauté automatique nationale

Il s'agit de **partager des expériences accumulées**, dans des domaines aussi divers que la robotique, le génie des

External Links

SAGIP
GDR MACS

CT CPNL actions

- 1 full day (in-person) + possible additional events (visio)
- 2023:
 - Invited session on MPC at ECC
 - Two sessions for CT CPNL at 1st SAGIP Congress
- 2024:
 - CFP for 2nd SAGIP Congress (<https://sagip2024.sciencesconf.org/>)
 - Lyon, 29-31 May, 2024
 - Abstract submission deadline: Feb. 15th, 2024
 - > abstract may concern already published conference or journal paper
 - > choose CT CPNL when submitting your abstract
 - CFP for IFAC NMPC (<https://nmpc2024.org>)
 - Kyoto, 21-24 August, 2024
 - Paper submission deadline: Dec. 18th, 2023
 - Possible action: organization of a summer school on MPC in France
 - Contact us if you are interested in the project!



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